BDDs and their application in SMT solving

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Outline

1 binary decision diagrams (BDDs)

2 theory of bitvectors (BV)

BDD-based SMT solving of BV

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1 binary decision diagrams (BDDs)

- definition
- operations on BDDs
- libraries and applications
- 2 theory of bitvectors (BV)

BDD-based SMT solving of BV

Binary decision diagrams (BDDs)



investigated by Randal Bryant since 1986

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"one of the only really fundamental data structures that came out in the last twenty-five years"

Donald Knuth, 2008



A binary decision diagram (BDD) is a finite rooted directed acyclic graph with two kinds of nodes and two kinds of edges:

- each terminal node is labeled with 0 or 1,
- each nonterminal node is labeled with a Boolean variable and has a low successor and a high successor.



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Semantics of BDDs

- **a** BDD with variables x_1, \ldots, x_n describes a Boolean function $f(x_1, \ldots, x_n)$
- the value of *f*(*x*₁,...,*x*_n) is the value of the terminal node reached from the root by following the high successor whenever the current variable is 1 and the low successor otherwise



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alternatively, a BDD can represent the set of assignments leading to node 1









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Properties of BDDs

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some BDDs are exponential in the number of variables regardless their order, e.g., BDDs representing the $\lfloor n/2 \rfloor$ -th bit of the product of two *n*-bit numbers

Construction of BDDs

BDDs for basic Boolean functions



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negation ¬B

■ replace 1 with 0 and vice versa



Construction of BDDs

BDDs for basic Boolean functions



negation $\neg B$

■ replace 1 with 0 and vice versa



1
$$b \star d$$
 where $b, d \in \{0, 1\} \longrightarrow b \star d$





binary operation $B \star D$ for $\star \in \{\land, \lor, xor, \ldots\}$



5 reduce the resulting BDD






















































- 1 if the root is labeled with x_i , then take the high successor as the root if b = 1 and the low successor otherwise
- 2 going from top to bottom, each edge leading to a node labeled with x_i is reconnected to its high successor if b = 1 and its low successor otherwise
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quantifiers

$$\exists x.B \equiv B[x \leftarrow 1] \lor B[x \leftarrow 0] \exists \forall x.B \equiv B[x \leftarrow 1] \land B[x \leftarrow 0]$$

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complexity and implementation

- all the mentioned operations need only polynomial time when applied to BDDs with the same variable order (and when cache is used)
- in implementations, each node in represented BDDs is stored only once
- equivalence check is constant
- a formula is satisfiable iff the corresponding BDD is not 0



Libraries for BDDs and their applications

libraries

- implementations use also negation flags on edges (increases the number of isomorphic subgraphs)
- optimized BDD libraries BuDDy, CUDD, Sylvan, Adiar,...
- offer algorithms for automatic improvement of variable order (sifting)
- support of other diagrams, e.g., zero-suppressed decision diagrams (ZDD)

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applications

- symbolic model checking
- synthesis of logical circuits
- used in other highly efficient libraries, e.g., in ω -automata library Spot
- SAT and SMT solving

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 - standard approach to SMT solving
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SAT solving

- satisfiability of propositional formulae
- Is $((x \land \neg y \land \neg z) \lor (\neg x \land \neg y)) \land (z \lor y)$ satisfiable?

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SMT solving

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- Is $\forall y \ (y \ge 0 \implies \exists x \cdot y = x \cdot x)$ satisfiable/valid?
- NO for integers, YES for reals
- SMT = satisfiability modulo theory
- decidability and complexity depends on the theory

Theory of fixed-size bitvectors

- BV = theory of bitvectors / bitvector logic
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- for each n > 0, sort [n] = bitvectors of length n
- functions
 - constants: $\mathbf{0}_{[n]}, \mathbf{1}_{[n]}, \ldots$
 - bit-wise logic operations: not[n], and[n], or[n]
 - arithmetic operations with overflows: $+_{[n]}, *_{[n]}, /_{[n]}^{s}, /_{[n]}^{u}$...
 - bit-wise left/right shift: shl[n], shr[n]
 - concatenation: concat_[m,n]
 - extraction: extract_[m,i,j]
 - [uninterpretted functions]

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 - [uninterpretted functions]
- predicates
 - equality: $=_{[n]}$
 - signed/unsigned less than (or equal): $<_{[n]}^{s}, <_{[n]}^{u}, \leq_{[n]}^{s}, \leq_{[n]}^{u}$

```
unsigned char x = input();
if (x > 100) {
    unsigned char y = 4 * x + 1;
    assert(x < y);
}
```

the assertion can be violated \iff

 $x_{[8]} >_{[8]}^{u} 100_{[8]} \land \neg (x_{[8]} <_{[8]}^{u} 4_{[8]} *_{[8]} x_{[8]} +_{[8]} 1_{[8]})$ is satisfiable

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- QF_BV = quantifier-free fragment of BV
- verification of safety properties
- automatic test generation

. . . .

```
unsigned char x = input();
while (x != 0) {
    x = x - 3;
}
```

the program always terminates \iff

 $\forall x_{[8]} \exists y_{[8]} . x_{[8]} - {}_{[8]} 3_{[8]} * {}_{[8]} y_{[8]} = {}_{[8]} 0_{[8]}$ is satisfiable/valid

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- proving termination
- computation and application of loop summaries
- program synthesis

...

	uninterpreted functions	encoding of bitvector lengths	
		unary	binary
QF_BV	no	NP	NEXPTIME
	yes	NP	NEXPTIME
BV	no	PSPACE	AEXP(poly)
	yes	NEXPTIME	2-NEXPTIME

-complete in all cases

- AEXP(poly) = problems solvable by alternating Turing machines with polynomial number of alternations in exponential time
- $\blacksquare \textbf{ NEXPTIME} \subseteq \textbf{AEXP}(\mathsf{poly}) \subseteq \textbf{EXPSPACE}$

- bit-blasting and SAT solving
- each bitvector variable $x_{[n]}$ can be seen as a sequence of *n* Boolean variables $x_{n-1}x_{n-2}...x_1x_0$
- bitvector functions and relations can be transformed into Boolean operations

$$x_{[2]} + [2] y_{[2]} = [2] \mathbf{1}_{[2]}$$

$$\downarrow$$

$$"x_1 x_0 + y_1 y_0 = \mathbf{01}"$$

$$\downarrow$$

$$(x_0 \iff \neg y_0) \land (x_1 \iff y_1)$$

$$\psi = \forall x \exists y . \varphi(x, y)$$

$$\begin{array}{l} \psi = \forall x \exists y \, . \, \varphi(x, y) \\ & \downarrow \\ \\ \\ \forall x \, . \, \varphi(x, f_y(x)) \end{array} \end{array}$$






Traditional approach to SMT solving of BV



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- BDD-based SMT solving of BV
 - naïve algorithm
 - algorithm improvements
 - Q3B
 - based on joint work with Martin Jonáš [SAT'16, SAT'17, ICTAC'18, IPL'18, CAV'19]



- **1** translate BV formula φ to BDD B_{φ} representing its models
- 2 check if B_{φ} represents some model, i.e., $B_{\varphi} \neq 0$ YES: φ is satisfiable
 - NO: φ is unsatisfiable

a translate each term of type [*n*] into a vector of *n* of BDDs that represents the function given by the term

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 $x_{[3]} +_{[3]} y_{[3]}$ " $x_2 x_1 x_0 + y_2 y_1 y_0$ "

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 $t_{[3]} =_{[3]} t'_{[3]} \qquad (B_2 \iff B'_2) \land (B_1 \iff B'_1) \land (B_0 \iff B'_0)$

b translate each atomic subformula to a single BDD representing its models



c apply logical connectives and quantifiers of the formula to BDDs corresponding to subformulae

 $\forall x_{[3]} . \psi$ process as $\forall x_2 \forall x_1 \forall x_0 . B_{\psi}$

Observations

the algorithm works well as long as the constructed BDDs are small
quantification of variables usually reduces the BDD size



sizes of BDDs corresponding to all quantified subformulas in SMT-LIB benchmarks for BV logic

GOAL: reduce the size of constructed BDDs

- modification of the input formula
 - move quantifiers downwards
 - eliminate variables or lower their bitwidth
 - simplify the formula
- approximations using less Boolean variables
- abstractions of bitvector operations with BDDs of limited size

push quantifiers in the formula downwards (miniscoping)

 $\forall x . \varphi(x) \lor \psi \rightsquigarrow \forall x (\varphi(x)) \lor \psi \qquad \forall x . \varphi(x) \land \psi(x) \rightsquigarrow \forall x (\varphi(x)) \land \forall x (\psi(x))$ $\exists x . \varphi(x) \land \psi \rightsquigarrow \exists x (\varphi(x)) \land \psi \qquad \exists x . \varphi(x) \lor \psi(x) \rightsquigarrow \exists x (\varphi(x)) \lor \exists x (\psi(x))$

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eliminate variables in the formula by equality resolution

 $\forall x . \neg (x = t) \lor \varphi(x) \quad \rightsquigarrow \quad \varphi(t) \qquad \qquad \exists x . x = t \land \varphi(x) \quad \rightsquigarrow \quad \varphi(t)$

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simplify the formula with unconstrained or partly constrained terms

- unconstrained term = term that can have an arbitrary value
- let u be a free or existentially quantified unconstrained variable
- let v be a fresh variable

 $u + 5 * (y + z) \rightsquigarrow v \qquad \qquad u_{[n]} *_{[n]} 4_{[n]} \rightsquigarrow \text{concat}_{[n-2,2]}(v_{[n-2]}, 0_{[2]})$

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let u be universally quantified unconstrained variable

 $t <^u u \rightsquigarrow false \qquad t \le^u u \rightsquigarrow t = 0$

Algorithm improvements: approximations

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 φ = formula φ with reduced existentially quantified variables

 φ is satisfiable $\implies \varphi$ is satisfiable

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overapproximation

 $\overline{\varphi}$ = formula φ with reduced universally quantified variables

 $\overline{\varphi}$ is unsatisfiable $\implies \varphi$ is unsatisfiable

satisfiability can be sometimes decided without costly computations

abstract bitvector operations by computing only BDDs under a given node limit





satisfiability can be sometimes decided without costly computations

 $x_{[3]} + {}_{[3]} y_{[3]}$

abstract bitvector operations by computing only BDDs under a given node limit



- satisfiability can be sometimes decided without costly computations
- abstract bitvector operations by computing only BDDs under a given node limit
 - adopt BDD operations to handle ? correctly

$$? \land B = \begin{cases} \boxed{0} & \text{if } B = \boxed{0} \\ ? & \text{otherwise} \end{cases}$$

satisfiability can be sometimes decided without costly computations

- abstract bitvector operations by computing only BDDs under a given node limit
 - two modes for evaluation of atomic subformulae



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 pesimist claims satisfiability optimist claims unsatisfiability formula is unsatisfiable Q3B



Evaluation of SMT solvers for BV

results from 2019

CPU time limit 20 minutes and memory limit 16 GiB per formula

		solved by			
family	total	Boolector	CVC4	Q3B	Z3
2017-Preiner-keymaera	4035	4019	3996	4009	4031
2017-Preiner-psyco	194	193	190	182	194
2017-Preiner-scholl-smt08	374	306	248	317	272
2017-Preiner-tptp	73	69	73	73	73
2017-Preiner-UAutomizer	153	152	151	153	153
20170501-Heizmann-UAutomizer	131	30	128	124	32
2018-Preiner-cav18	600	549	565	565	550
wintersteiger	191	162	174	182	163
Total	5751	5480	5525	5605	5468

Evaluation of SMT solvers for BV



2016 1st in the Main Track of the BV division in Sequential Performance and Parallel Performance 2017 1st in the Main Track of the BV division in Sequential Performance and Parallel Performance 2019 2nd in the Single Query Track of the BV division in Sequential Performance, Parallel Performance, SAT Performance, and 24 seconds Performance 2022 2nd in the Single Query Track of the BV division in Sequential Performance, Parallel Performance, SAT Performance, UNSAT Performance, and 1st in 24 seconds Performance

Ongoing research and development of Q3B

- improved caching and static analysis of BV formulae
- advanced sifting algorithms
- use of partial BDDs

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Conclusions and references

BDDs have known limitations, but also great advantages and efficient libraries

■ in the context of SAT/SMT-solving, BDDs like quantifiers
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